F08NGF (SORMHR/DORMHR) – NAG Fortran Library Routine Document

Note. Before using this routine, please read the Users' Note for your implementation to check the interpretation of bold italicised terms and other implementation-dependent details.

1 Purpose

F08NGF (SORMHR/DORMHR) multiplies an arbitrary real matrix C by the real orthogonal matrix Q which was determined by F08NEF (SGEHRD/DGEHRD) when reducing a real general matrix to Hessenberg form.

2 Specification

```
SUBROUTINE FO8NGF(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C,

LDC, WORK, LWORK, INFO)

ENTRY sormhr(SIDE, TRANS, M, N, ILO, IHI, A, LDA, TAU, C,

LDC, WORK, LWORK, INFO)

INTEGER M, N, ILO, IHI, LDA, LDC, LWORK, INFO

real A(LDA,*), TAU(*), C(LDC,*), WORK(LWORK)

CHARACTER*1 SIDE, TRANS
```

The ENTRY statement enables the routine to be called by its LAPACK name.

3 Description

This routine is intended to be used following a call to F08NEF (SGEHRD/DGEHRD), which reduces a real general matrix A to upper Hessenberg form H by an orthogonal similarity transformation: $A = QHQ^T$. F08NEF represents the matrix Q as a product of $i_{hi} - i_{lo}$ elementary reflectors. Here i_{lo} and i_{hi} are values determined by F08NHF (SGEBAL/DGEBAL) when balancing the matrix; if the matrix has not been balanced, $i_{lo} = 1$ and $i_{hi} = n$.

This routine may be used to form one of the matrix products

$$QC, Q^TC, CQ \text{ or } CQ^T,$$

overwriting the result on C (which may be any real rectangular matrix).

A common application of this routine is to transform a matrix V of eigenvectors of H to the matrix QV of eigenvectors of A.

4 References

[1] Golub G H and van Loan C F (1996) Matrix Computations Johns Hopkins University Press (3rd Edition), Baltimore

5 Parameters

1: SIDE — CHARACTER*1

Input

On entry: indicates how Q or Q^T is to be applied to C as follows:

```
if SIDE = 'L', then Q or Q^T is applied to C from the left; if SIDE = 'R', then Q or Q^T is applied to C from the right.
```

Constraint: SIDE = 'L' or 'R'.

2: TRANS — CHARACTER*1

Input

On entry: indicates whether Q or Q^T is to be applied to C as follows:

if TRANS = 'N', then Q is applied to C; if TRANS = 'T', then Q^T is applied to C.

Constraint: TRANS = 'N' or 'T'.

3: M — INTEGER

Input

On entry: m, the number of rows of the matrix C; m is also the order of Q if SIDE = 'L'.

Constraint: M > 0.

4: N — INTEGER

Input

On entry: n, the number of columns of the matrix C; n is also the order of Q if SIDE = 'R'.

Constraint: $N \ge 0$.

5: ILO — INTEGER

Input

6: IHI — INTEGER

Input

On entry: these **must** be the same parameters ILO and IHI, respectively, as supplied to F08NEF (SGEHRD/DGEHRD).

Constraints:

 $1 \le ILO \le IHI \le M \text{ if SIDE} = L' \text{ and } M > 0;$

ILO = 1 and IHI = 0 if SIDE = 'L' and M = 0;

 $1 \le ILO \le IHI \le N$ if SIDE = 'R' and N > 0;

ILO = 1 and IHI = 0 if SIDE = R' and N = 0.

7: A(LDA,*) - real array

Input

Note: the second dimension of the array A must be at least max(1,M) if SIDE = 'L' and at least max(1,N) if SIDE = 'R'.

On entry: details of the vectors which define the elementary reflectors, as returned by F08NEF (SGEHRD/DGEHRD).

8: LDA — INTEGER

Input

On entry: the first dimension of the array A as declared in the (sub)program from which F08NGF (SORMHR/DORMHR) is called.

Constraints:

 $LDA \ge max(1,M)$ if SIDE = 'L',

 $LDA \ge max(1,N)$ if SIDE = R'.

9: TAU(*) - real array

Input

Note: the dimension of the array TAU must be at least max(1,M-1) if SIDE = 'L' and at least max(1,N-1) if SIDE = 'R'.

On entry: further details of the elementary reflectors, as returned by F08NEF (SGEHRD/DGEHRD).

10: C(LDC,*) - real array

Input/Output

Note: the second dimension of the array C must be at least max(1,N).

On entry: the m by n matrix C.

On exit: C is overwritten by QC or Q^TC or CQ^T or CQ as specified by SIDE and TRANS.

11: LDC — INTEGER Input

On entry: the first dimension of the array C as declared in the (sub)program from which F08NGF (SORMHR/DORMHR) is called.

Constraint: LDC $\geq \max(1,M)$.

12: WORK(LWORK) — real array

Work space

On exit: if INFO = 0, WORK(1) contains the minimum value of LWORK required for optimum performance.

13: LWORK — INTEGER

Input

On entry: the dimension of the array WORK as declared in the (sub)program from which F08NGF (SORMHR/DORMHR) is called.

Suggested value: for optimum performance LWORK should be at least N \times nb if SIDE = 'L' and at least M \times nb if SIDE = 'R', where nb is the **blocksize**.

Constraints:

LWORK
$$\geq \max(1,N)$$
 if SIDE = 'L',
LWORK $\geq \max(1,M)$ if SIDE = 'R'.

14: INFO — INTEGER

Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

7 Accuracy

The computed result differs from the exact result by a matrix E such that

$$||E||_2 = O(\epsilon)||C||_2$$

where ϵ is the *machine precision*.

8 Further Comments

The total number of floating-point operations is approximately $2nq^2$ if SIDE = 'L' and $2mq^2$ if SIDE = 'R', where $q=i_{hi}-i_{lo}$.

The complex analogue of this routine is F08NUF (CUNMHR/ZUNMHR).

9 Example

To compute all the eigenvalues of the matrix A, where

$$A = \begin{pmatrix} 0.35 & 0.45 & -0.14 & -0.17 \\ 0.09 & 0.07 & -0.54 & 0.35 \\ -0.44 & -0.33 & -0.03 & 0.17 \\ 0.25 & -0.32 & -0.13 & 0.11 \end{pmatrix},$$

and those eigenvectors which correspond to eigenvalues λ such that Re(λ) < 0. Here A is general and must first be reduced to upper Hessenberg form H by F08NEF (SGEHRD/DGEHRD). The program then calls F08PEF (SHSEQR/DHSEQR) to compute the eigenvalues, and F08PKF (SHSEIN/DHSEIN) to compute the required eigenvectors of H by inverse iteration. Finally F08NGF (SORMHR/DORMHR) is called to transform the eigenvectors of H back to eigenvectors of the original matrix A.

9.1 Program Text

Note. The listing of the example program presented below uses bold italicised terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
FO8NGF Example Program Text
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.. Parameters ..
                 NIN, NOUT
INTEGER
PARAMETER
                 (NIN=5, NOUT=6)
INTEGER
                 NMAX, LDA, LDH, LDZ, LWORK, LDVL, LDVR
                 (NMAX=8,LDA=NMAX,LDH=NMAX,LDZ=1,LWORK=64*NMAX,
PARAMETER
                 LDVL=NMAX,LDVR=NMAX)
.. Local Scalars ..
real
                 THRESH
INTEGER
                 I, IFAIL, INFO, J, M, N
.. Local Arrays ..
                 A(LDA, NMAX), H(LDH, NMAX), TAU(NMAX),
real
                 VL(LDVL, NMAX), VR(LDVR, NMAX), WI(NMAX),
                 WORK(LWORK), WR(NMAX), Z(LDZ,1)
INTEGER
                 IFAILL(NMAX), IFAILR(NMAX)
                 SELECT (NMAX)
LOGICAL
.. External Subroutines ..
                sgehrd, shsein, shseqr, sormhr, F06QFF, X04CAF
EXTERNAL
.. Executable Statements ..
WRITE (NOUT,*) 'FO8NGF Example Program Results'
Skip heading in data file
READ (NIN,*)
READ (NIN,*) N
IF (N.LE.NMAX) THEN
   Read A from data file
   READ (NIN,*) ((A(I,J),J=1,N),I=1,N)
   READ (NIN,*) THRESH
   Reduce A to upper Hessenberg form H = (Q**T)*A*Q
   CALL sgehrd(N,1,N,A,LDA,TAU,WORK,LWORK,INFO)
   Copy A to H
   CALL F06QFF('General', N, N, A, LDA, H, LDH)
   Calculate the eigenvalues of H (same as A)
   CALL shseqr('Eigenvalues', 'No vectors', N, 1, N, H, LDH, WR, WI, Z, LDZ,
               WORK, LWORK, INFO)
   WRITE (NOUT,*)
   IF (INFO.GT.O) THEN
      WRITE (NOUT,*) 'Failure to converge.'
      WRITE (NOUT,*) 'Eigenvalues'
      WRITE (NOUT, 99999) (' (', WR(I), ', ', WI(I), ')', I=1, N)
      DO 20 I = 1, N
         SELECT(I) = WR(I) .LT. THRESH
```

```
20
            CONTINUE
            Calculate the eigenvectors of H (as specified by SELECT),
            storing the result in VR
            CALL shsein('Right','QR','No\ initial\ vectors',SELECT,N,A,
                         LDA, WR, WI, VL, LDVL, VR, LDVR, N, M, WORK, IFAILL,
                         IFAILR, INFO)
            Calculate the eigenvectors of A = Q * (eigenvectors of H)
            CALL sormhr('Left', 'No transpose', N, M, 1, N, A, LDA, TAU, VR, LDVR,
                         WORK, LWORK, INFO)
            Print eigenvectors
            WRITE (NOUT,*)
            IFAIL = 0
            CALL XO4CAF('General',' ',N,M,VR,LDVR,
                         'Contents of array VR', IFAIL)
         END IF
      END IF
      STOP
99999 FORMAT (1X,A,F8.4,A,F8.4,A)
      END
```

9.2 Program Data

9.3 Program Results

FO8NGF Example Program Results